# **Quick Start Guide**



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TDHBG2500P100\_0v6 For evaluation purposes only

Design files and more at transphormusa.com/hb25kit

# TDHBG25000P100-KIT

**Evaluation Platform** 2.5kW half-bridge synchronous buck or boost

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as001.3

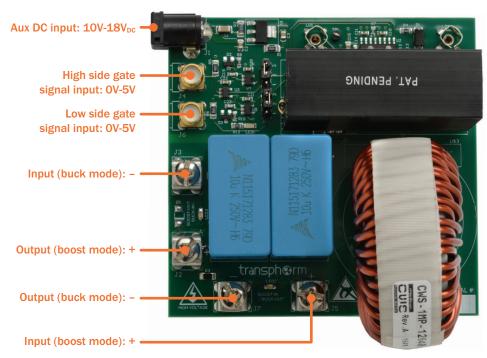
Highest Performance, Highest Reliability GaN

12/2017

## **Equipment Needed**

- The TDHBG2500P100\_0v6 board
- High-voltage DC power supply for input/output
  - 400V<sub>DC</sub> maximum
  - 2.5kW maximum
- Low-voltage DC power supply for auxiliary voltage
  - 10V min, 18V max
- Pulse generator or direct gate driver for logic inputs
  - Nominal OV to 5V
  - Typical frequency is 100kHz; other frequencies may require a different inductor
  - SMA coaxial connectors
- 450V low ESR electrolytic capacitors capable of 2Arms and 7Arms ripple current

# **Step 1: Connect the Board**



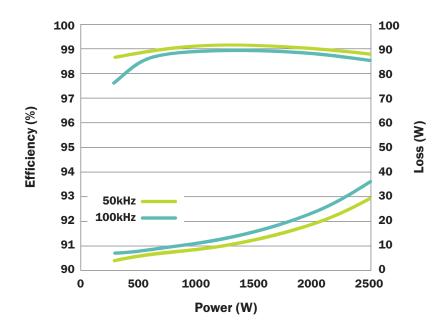
#### Warning:

Inductor is designed for 100kHz operation; a different inductor may be needed for a different frequency. Please refer to the TDHBG2500P100 User Guide.

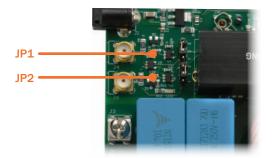
# **Step 4: Power-up the Board**

- The TDHBG2500P100 board can deliver 2500W with forced air cooling when configured as
  - 200V to 400V boost, 100kHz, or
  - + 400V to 200V buck, 100kHz
- Different input/output voltage and power can be chosen, however
  - Input/output voltage should not exceed 400V
  - In each GaN FET, the rms current should not exceed 9A
  - Users should monitor the device temperature to make sure they are not being overheated by excessive power during the test
- Driver deadtime is preset to 120ns for typical operation and can be adjusted for different operating conditions; please refer to the TDHBG2500P100 User Guide for a detailed description

#### Typical Efficiency for a Boost 200V:400V Converter

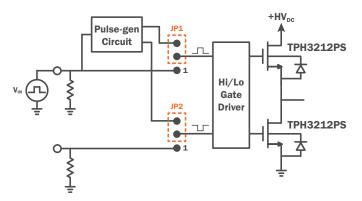


## **Step 2: Set the Jumpers**

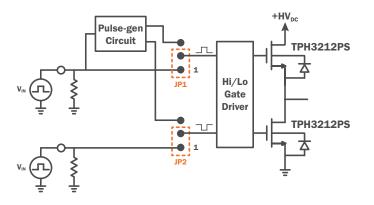


#### **Jumper Positions**

**1.** Using single source for either buck or boost mode using synchronous rectification



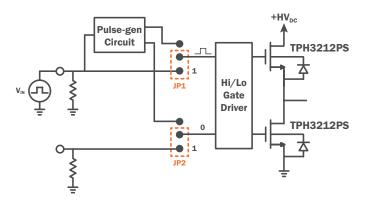
2. Using two single sources with synchronous rectification



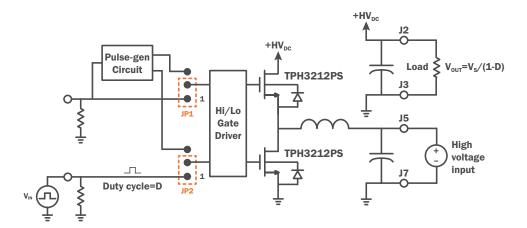
#### Warning:

During non-synchronous operation, the freewheeling diode will get hot resulting in decreased efficiency.

3. Buck mode without synchronous rectification (not recommended)



4. Boost mode without synchronous rectification (not recommended)

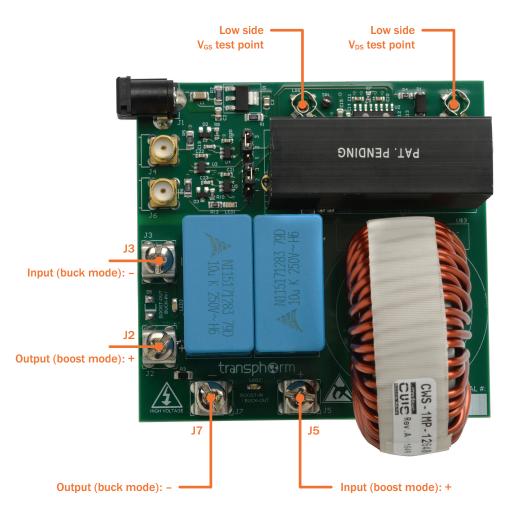


## **Step 3: Attach Probes**

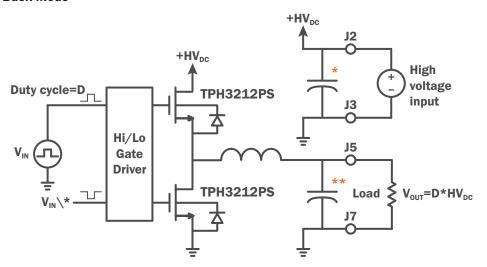
#### **Connect in Buck and Boost Modes**

#### Warning:

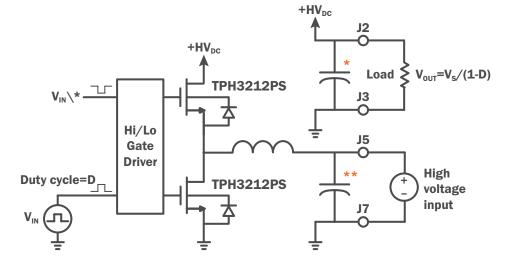
Driver deadtime is preset to 120ns for typical operation and can be adjusted for different operating conditions. Please refer to the TDHBG2500P100 User Guide.



**Buck Mode** 



#### **Boost Mode**



\* 450V low ESR electrolytic capacitor capable of 7Arms ripple current

\*\* 450V low ESR electrolytic capacitor capable of 2Arms ripple current